

### **Rolawn Delivery Method excluding inside M25 Motorway**

The customer must ensure that the delivery vehicle has safe access to the point of unloading.

Delivery vehicles are generally 11 metres (36') long, 2.5 metres (8' 2") wide, 4.6 metres (15') high.

Please allow 3 metres (10') clearance to the rear of the vehicle for operation of the tail lift.

Deliveries are made on pallets. The pallets are unloaded using a hydraulic platform or tail lift which lowers the pallet to ground level. The driver then uses a small manual pallet truck to manually pull the pallet to the nearest hard-standing, flat surface to customer's property. We undertake to place the goods as close to the customer's property as is deemed safe by the driver.

**Please note that manual pallet trucks can only operate on tarmac, concrete and paved areas which must be level and clear of obstructions.**

Manual pallet trucks cannot operate on gravel, earth, grass or any other type of non-solid surface.

### **Rolawn Delivery Method inside M25 Motorway**

The customer must ensure that the delivery vehicle has safe access to the point of unloading.

Delivery vehicles are generally 9.2 metres (30') long, 2.5 metres (8' 2") wide, 3.6 metres (12') high or approximately the same size as a large dustbin lorry.

Please allow 2 metres (6') clearance to each side of the vehicle for operation of the hydraulic crane. Please also check for overhead obstructions such as power and phone cables or tree branches in the offloading location.

Deliveries are made on pallets. The pallets are unloaded using a vehicle mounted hydraulic crane which lowers the pallet to ground level. Rolawn undertake to place the goods as close to the position required within the working reach of the crane as is deemed safe by the driver.

**Please note that vehicle mounted hydraulic cranes cannot operate in close proximity to overhead power cables, telephone cables, tree branches and other overhead obstructions.**

The cranes cannot be used to lift pallets over parked vehicles.